

Modelling Geometric Objects with ISO 15926

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Actual problems Oil and Gas Industry

- Scenarios are replaced in 3-4 years
- Projects lifecycle last more then 10 years

Owner, Manufactures, Engineering Contractors and Operators may use different Platforms

- Different project tools
- High-cost migration

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US\$15.8 billions for interoperability costs

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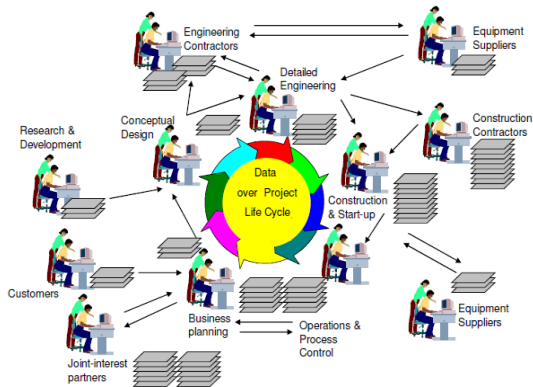
ISO15926 - Industrial automation systems and integration–Integration of life-cycle data for process plants including oil and gas production facilities

Why use ISO 15926?

- Life-cycle description
- Flexibility and Extensibility
- Information context
- Validation



Data over Project Life Cycle (modified from Pawsey, 2012)



Nowadays...

Part 1: Overview and fundamental principles

Part 2: DataModel, it that represent information common to users and process plants. In Natural Language: Grammar

Part 3: Geometry and topology

Part 4: Reference Data Library (RDL). In Natural Language: The dictionary

Part 7: Templates. In Natural Language: It is equivalent to a phrase book

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- Part 9: Implementation standards, with the focus on Façades, standard web servers, web services, and security
- Part 10: Formally named Implementation Methods for the Integration of Distributed Systems: Abstract Test Methods (draft)
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Defining objects

Template methodology

Complex objects must be defined as templates.

Part 3

A huge library of **basic** geometric terms.

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A huge library of **basic** geometric terms.

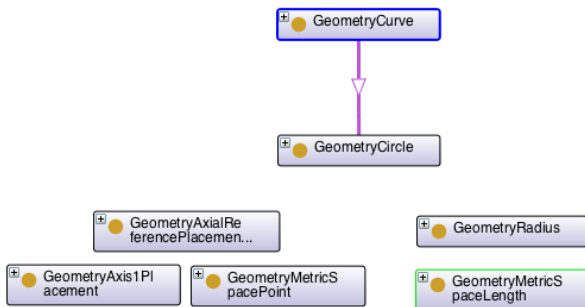
Identifying Part 3 elements

Circle definition in Part 3

An object is a **circle** if and only if: 1-it is **curve**; 2-it lies in a **plane**; 3- there is a centre point that is equi-distant from each point in the curve.

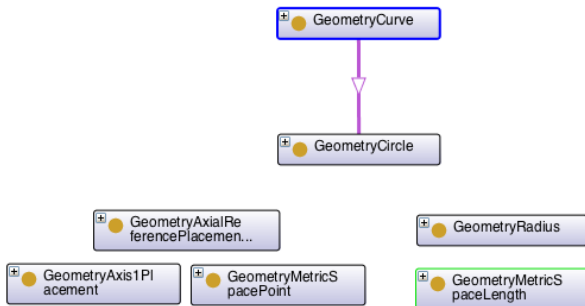
NOTE 2 A **circle** has the geometric properties: radius; center and plane. These properties can be given for a **circle** by a **axial_reference_placement** and a **radius**. A **circle** has two alternative values for the **axial_reference_placement** corresponding to opposite directions for the normal.

Identifying classes



Which templates are necessary?

Identifying classes



Which templates are necessary?

Modeling process steps

Definition of the signature, that describes the elements that compound the relationship;

Signature

Order	Rule	Type
1	hasProperty	Property
2	valPropertyValue	ExpressReal
3	hasScale	Scale

Modeling process steps

Definition of Axioms/Sentences in First Order Logic (FOL), that describes the semantics through the relations between the elements presented in the signature.

Axiom

$$\begin{aligned} \text{RealMagnitudeOfProperty}(x_1, x_2, x_3) \leftrightarrow \\ \text{property}(x_1) \wedge \text{ExpressReal}(x_2) \wedge \text{scale}(x_3) \wedge \\ \exists u (\text{MagnitudeOfProperty}(x_1, u, x_3) \wedge \\ \text{IdentificationByNumber}(x_2, u)) \end{aligned}$$

RealMagnitudeOfProperty

The template **RealMagnitudeOfProperty** is used to connect a concept classified as a **property** with a numeric value and a **scale**.

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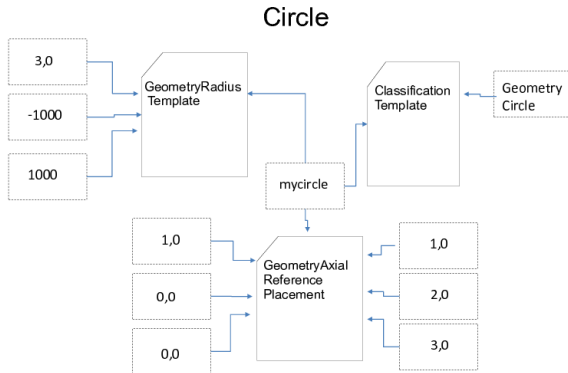
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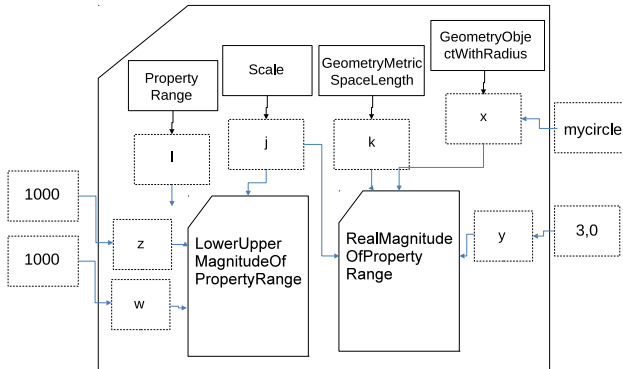
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GeometryRadiusTemplate

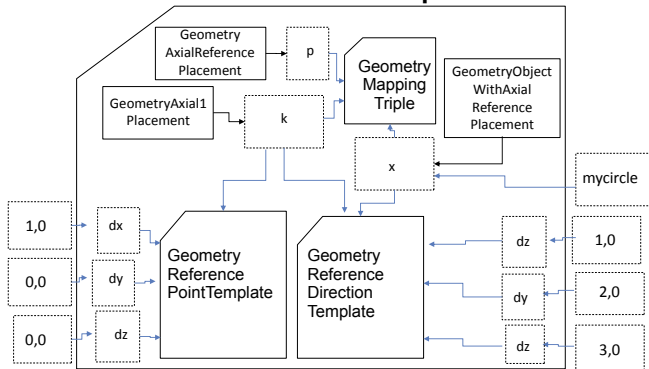


Order	Rule	Type
1	hasPossessor	ObjectWithRadius
2	hasRadius	RealNumber
3	hasLowerBound	RealNumber
4	hasUpperBound	RealNumber

$$\begin{aligned}
 \text{RadiusTemplate}(x, y, z, w) \leftrightarrow & \\
 & \text{ObjectWithRadius}(x) \wedge \text{RealNumber}(y) \wedge \text{RealNumber}(z) \wedge \\
 & \text{RealNumber}(w) \wedge \exists m (\text{radius}(m) \wedge \text{hasEnd1}(m, x_1) \\
 & \quad \wedge \text{hasEnd2}(m, k)) \wedge \\
 \exists k (\text{metric_space_length}(k) \wedge \exists j (& \\
 \quad \text{Scale}(j) \wedge \exists \ell (& \\
 \quad \quad \text{PropertyRange}(\ell) \wedge & \\
 \quad \quad \text{LowerUpperMagnitudeOfPropertyRange}(\ell, j, z, w) \wedge & \\
 \quad \quad \text{RealMagnitudeOfProperty}(k, y, j))) \wedge & \\
 \exists p (\text{MappingTriple}(m, x, k) \wedge \text{radius}(p)) &
 \end{aligned}$$

$$\begin{aligned} & \text{AxialReferencePlacementTemplate}(q, p_x, p_y, p_z, d_x, d_y, d_z) \leftrightarrow \\ & \text{ObjectWithAxialReferencePlacement}(q) \wedge \exists k(\\ & \quad \text{axis1_placement}(k) \wedge \\ & \quad \text{ReferencePointTemplate}(k, p_x, p_y, p_z) \wedge \\ & \quad \text{ReferenceDirectionTemplate}(k, d_x, d_y, d_z) \wedge \\ & \quad \exists p (\text{MappingTriple}(p, q, k) \wedge \\ & \quad \quad \text{axial_reference_placement}(p))) \end{aligned}$$

GeometryAxialReference PlacementTemplate



Further work

- Implement tools:
 - for domain experts
 - for users
- Develop ISO 15926 research subjects

Tools

Template Expander expands FOL definitions to basic terms

iRing Tools interoperate data in a ISO 15926-like approach

.15926 an environment to build and manipulate ISO 15926 compliant data

15926:8 OWL visualization

FOL2OWL translates FOL template axioms to OWL

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